

#### IABU Headquarters

Delta Electronics, Inc. Taoyuan1 31-1, Xingbang Road, Guishan Industrial Zone, Taoyuan County 33370, Taiwan, R.O.C. TEL: 886-3-362-6301 / FAX: 886-3-362-7267

#### Asia

#### Delta Electronics (Jiang Su) Ltd.

Wujiang Plant3 1688 Jiangxing East Road, Wujiang Economy Development Zone, Wujiang City, Jiang Su Province, People's Republic of China (Post code: 215200) TEL: 86-512-6340-3008 / FAX: 86-512-6340-7290

#### Delta Greentech (China) Co., Ltd.

238 Min-Xia Road, Cao-Lu Industry Zone, Pudong, Shanghai, People's Republic of China Post code : 201209 TEL: 021-58635678 / FAX: 021-58630003

#### Delta Electronics (Japan), Inc.

**Tokyo Office** Delta Shibadaimon Building, 2-1-14 Shibadaimon, Minato-Ku, Tokyo, 105-0012, Japan TEL: 81-3-5733-1111 / FAX: 81-3-5733-1211

#### Delta Electronics (Korea), Inc.

234-9, Duck Soo Building 7F, Nonhyun-Dong, Kangnam-Gu, Seoul, Korea 135-010 TEL: 82-2-515-5305 / FAX: 82-2-515-5302

#### Delta Electronics (Singapore) Pte. Ltd.

8 Kaki Bukit Road 2, #04-18 Ruby Warehouse Complex, Singapore 417841 TEL: 65-6747-5155 / FAX: 65-6744-9228

#### Delta Power Solutions (India) Pte. Ltd.

Plot No. 28, Sector-34, EHTP Gurgaon-122001 Haryana, India TEL: 91-124-416-9040 / FAX: 91-124-403-6045

#### America

**Delta Products Corporation (USA) Raleigh Offic** P.O. Box 12173,5101 Davis Drive, Research Triangle Park, NC 27709, U.S.A. TEL: 1-919-767-3813 / FAX: 1-919-767-3969

**Delta Products Corporation (Brazil)** Sao Paulo Office Rua Itapeva, Nº 26, 3º andar, Bela vista ZIP: 01332-000 - São Paulo - SP - Brasil TEL: 55-11-3568-3875 / FAX: 55-11-3568-3865

#### Europe

**Deltronics (The Netherlands) B.V.** Eindhoven Offic De Witbogt 15, 5652 AG Eindhoven, The Netherlands TEL: 31-40-2592850 / FAX: 31-40-2592851

\*Slight variations in appearance and specifications may exist between the catalogue and the actual product. We reserve the right to change the information in this catalogue without prior notice.







# **AC Servo Motor and Drive**

www.delta.com.tw/industrialautomation

# High Precision! High Response! Cost Effective!!

To meet the requirements of general-purpose machine tools and enhance the competitive advantage in servo system market, Delta Electronics, Inc. is pleased to announce that the new high-performance and cost-effective ASDA-B2 series servo motors and drives has launched into the market.

The power rating of the ASDA-B2 series is offered from 0.1kW to 3kW. The superior properties of this series emphasize on "built-in generic functions for general-purpose applications" and "avoiding variable costs from mechatronics integration. When Delta's ASDA-B2 series is in use, the users can conveniently complete assembly, wiring and operation setups. In addition, in switching from other brands to Delta's ASDA-B2 series, outstanding quality and features, and complete product lineup make the replacement is easy and quick to achieve. Using Delta ASDA-B2 series, not only the wiring and operation becomes much easier, and the requirements of general-purpose machine tools for the market could be satisfied as well. In addition, the customized solutions are available on request for different industries so that help ASDA-B2 series to be widely popular and always in demand by the customers in the field of industrial automation.



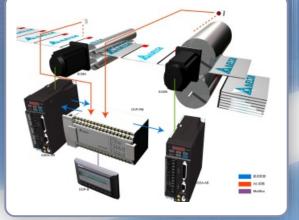
#### Transportation Machine



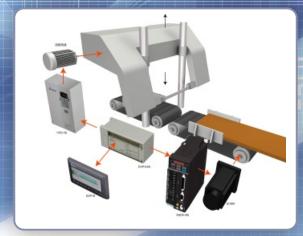
Electro-discharge Machine







awing Machine



#### Contents

#### 1.Introduction of ASDA-B2 Series

Features Model Explanation Product Line-up

#### 2. ASDA-B2 Series Servo DriveS

Part Names and Functions Standard Connection Examples Regenerative Resistor Safety Information Specifications Dimensions

# 4. ECMA Series Servo Motors 17 Specifications Dimensions Speed-Torque Curve (T-N Curves)

#### 5. Optional Accessories

6. Servo Drive, Servo Motor and Accessories Combinations 29

23

Pag

1



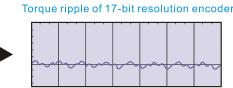
# **Features**

otio

# Implement High Precision Positioning Control

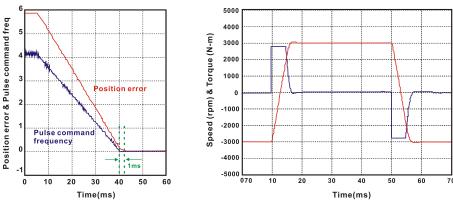
- High-resolution encoder with 17-bit (160,000 p/rev) is equipped as a standard feature which satisfies the application needs of high precision positioning control and stable rotation at low speed.
- New 17-bit resolution encoder can reduce cogging torque to enhance the precision of the motor.

Torque ripple of 2500ppr resolution encoder



220

- Outstanding response characteristic: Up to 550kHz frequency response and settling time is below 1ms.
- 10ms acceleration time from -3000r/min to 3000r/min when running without load.

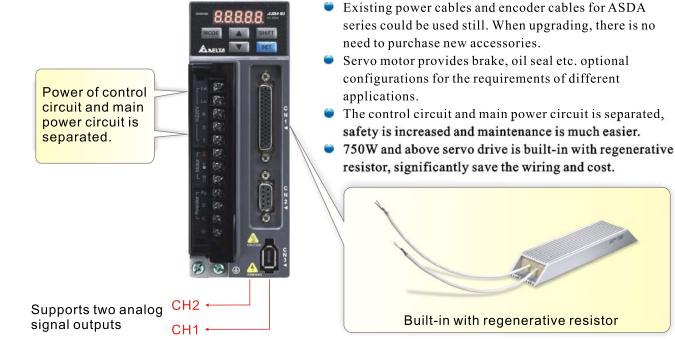


This example is frame size 60mm, 400W servo motor

# Satisfy Various Kinds Of Demands In The Industry

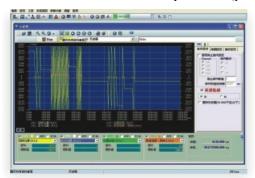
- Built-in position, speed and torque three control modes (speed and torque mode could be controlled via internal parameters or analog voltage command).
- High-speed line receiver command (4Mpps) is acceptable for high precision positioning control.
- Two auto notch filters are provided to suppress the mechanical resonance automatically and make the system operate more smoothly.
- Lead friction compensation parameter is specified for the application of circular interpolation, Z-axis motion and ball screw, etc. so as to reduce the loading of the controller.
- For bar feeder, etc. equipment requiring high torque output, motor protection parameter is offered to ensure that the mechanical system is hard to be damaged.

# Offer Easy-To-Install Solution For Simple Start-Up



# Fulfill Easy-To-Use Requirements For Versatile Operation

- Motor sizing software is offered for the customers to conduct the estimation of the equipment conveniently.
- ASDA-Soft configuration software (tuning software) is provided for the customers to meet the performance requirements quickly.
- Easy-to-use digital keypad is ideal for setting parameters and monitoring the servo drive and motor directly.
- Specific software communication cable ASD-CNUS0A08(Optional) for direct connection to PC increases communication quality and the convenience for operation. (please refer to optional accessories on catalogue page 24)



■ 4 channels on-line monitoring function (similar to a digital oscilloscope) is available. The monitoring data could be 16-bit (4 channels) and 32-bit (2channels) data.







	1006	1040.0	1.00	Line .	MATH:	Daing .	8 1	
51	491	Excession 1		0-00000000	8-30007777	3-0000000	A NUMBER OF	-
i l	AHE	D-CODERE S		6-0000000	B-BOOLPHTP	0-0000000	教育の時間にあったの	
6	APO	Concession in		0-0000000	8-80007777	3+00000000	ARRENAND	
8	434	D-COURSES		0.40000000	B-DOOPTTY	INCOMPANY.	教育的場合は新の下の	
•	494	D+0008888.3		8-88800000	B-BOXPYTY	0-00000000	R TREPERSON-CO	
6	305	10	128		5000	10	HEAD THEN	
6	POF	0-0000		6-000	8-802*	8-000	Calculation (Calculation (Calculation))	
R.	1993	Decision in the		4-899	8-36.97	8+0000	#081388#3HR	
	19327	D-COM		6.000	0.000*	0.000	MARKEN B. LINSTER	
	HDT	0+0000		6-888	8-802*	8+0000	# Orbitace Parks	
6	(094	6					松正和総選邦	
1	18041	22409		14	30767	LADER .	NULLACEN.入口の時間時間の最早期41日	
2	9045	15(4)		4	10767	14052	<b>期代表的ACOPPERSON</b>	
2	1091	04/82			30%	14052	植出品植物3点 建塑塑板量手数相互	
+	1040	LANE L		4	30767	LADED	現代が年期入び時間運動量が量が定	
5	0071	12024			32797	10000	REPORT DIFFERENCE	
<b>b</b>	COPU	04.030		1.0	20767	LADER	Watering and the second s	
17	0949	0.0494		4	16797	14762	电波波出版:	
	0084	10,004		1	30%	LAUNE:	教育会会議のご何の提供の自由工	
Ð.	19.08	5		1	3	2	30TVL REPORTER	
0	DOPL	0	100	-000	100		補助物理解会はと学校生活工作用会業的	
	DOPD	9	-	-800	100		新北部市時期のいたの運作曲村正確の共産産目	
	540	D.	100	-5000	5990		1000年度103-007587	
8		0	100	-9008	1000		Million Million Convert	
2	140	-40			149	140		

■ Multi-functional parameter editor function helps the users to edit, modify, upload / download and print desired parameters in real-time.



# **Model Explanation**

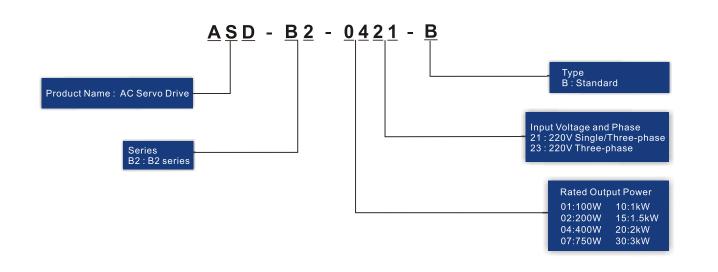
Notio

# **Product Line-up**

2

220\

#### ASDA-B2 Series Servo Drive



# ECMA Series Servo Motor

 ECM
 A - C 2 0 6 0 2 E
 S

 Product Name
 Standard Shaft Dimensions : S

 ECM: Electrical Commutation Motor
 Standard Shaft Dimensions : 7=14mm

 Driving Type
 A:AC Servo Motor

 A:AC Servo Motor
 Standard Shaft A

 B: Series
 Rated Output Power

 C:220V/13000rpm
 F

 E:220V/1500rpm
 Motor Frame Size

 Motor Frame Size
 Motor Frame Size

 Motor Frame Size
 Motor Mit Dimension

 F: 220V/13000rpm
 E: 220V/1000rpm

 F: 220V/1500rpm
 B: 60mm

 C: 220V/1000rpm
 B: 130mm

 B: 80mm
 18: 180mm

 0: 80mm
 18: 180mm

 0: 500W
 30: 3kW

# Image: Displaying the system <th

#### Note: Rotary Magnetic Encoder will be available gradually from March, 2010

5







Note: The boxes ( $\Box$ ) in the servo motor model names are for optional configurations (keyway, brake and oil seal).

# **Part Names and Functions**

• LED Display

lotio

■ The 5 digit, 7 segment LED displays the servo status or fault codes.

#### • Charge LED -

A lit LED indicates that either power is connected to the servo drive or a residual charge is present in the drive's internal power components.

#### • **Operation Panel**

 Used function keys to perform status display, monitor and diagnostic, function and parameter setting.Function Keys:
 MODE : Press this key to select/change mode

SHIFT : Press this key to shift cursor to the left
▲ : Press this key to increase values on the display
▼ : Press this key to decrease values on the display
SET : Press this key to store data

- Control Circuit Terminal (L1c, L2c)
- Used to connect 100~230Vac, 50/60Hz single-phase or three-phase VAC supply.
- Main Circuit Terminal -(R, S, T)
  - Used to connect 200~230Vac, 50/60Hz commercial power supply.
- Servo Motor Output (U, V, W)
  - Used to connect servo motor. Never connect the output terminal to main circuit power as the AC drive may be destroyed beyond repair if incorrect cables are connected to the output terminals.
- Internal & External Regenerative Resistor Terminal
  - 1. When using an external resistor, connect it to P⊕ and C, and ensure an open circuit between P⊕ and D.
  - 2. When using an internal resistor, ensure the circuit is closed between P⊕ and D, and the circuit is open between P⊕ and C.
  - When using external braking unit, connect braking unit to P⊕ and ⊖, and ensure an open circuit between P⊕ and D, and P⊕ and C.

• Ground Terminal

7⁄

■ Used to connect grounding wire of power supply and servo motor.



220





#### • I/O Interface

Used to connect Delta's DVP series PLC or other external controllers for controlling I/O signals.

#### **Motor Encoder Interface**

Used to connect the encoder of the servo motor

#### Serial Communication Port

■ Used to connect PLC, HMI, etc. controllers for RS-485 / RS-232 serial communication.

#### Analog Voltage Output Terminal

■ Used to provide two analog monitor outputs, MON1 and MON2.

#### Heatsink

■ Used to secure servo drive and for hear dissipation.

1otio

9

# **Standard Connection Example**

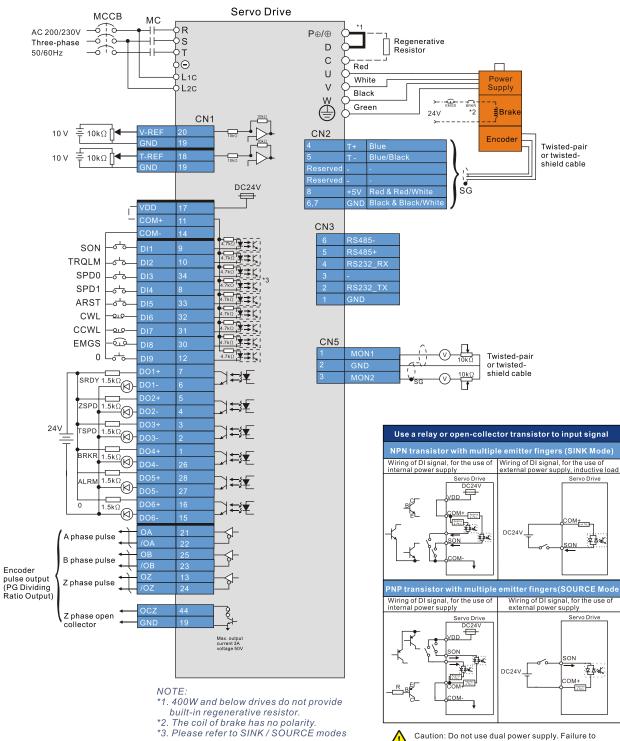
# Position (Pt) Control Mode (for Pulse Command Input)

#### Servo Drive MCCB мс -AC 200/230V P⊕/⊕ bs 5 Regenerative Resistor Three-phase D 50/60Hz -6 bт С þΘ Red U Max. ii pulse frequer is 200k ¢L1C . White [ V ÓL2C Black Ŵ CN1 <u></u>\_\_\_\_\_\_× Green 24V Pulse input (Line driver) X ...... CN2 Max. inpu Twisted-pair or twisted-shield cable 10 V ≑ 10kΩ∏ ← High-speed pulse input (Line receiver) +5V Red & Re DC24V GND Black & B K CN3 Max. inpu pulse Approx. is 200kpr 51Ω 51Ω RS485-7κΩ ₹\$К, SON ⊢⊶ RS232 R) CCLR ---тсмо ----тсм1 🖵 — <sup>κΩ</sup> **≭**≭K, ARST L-0-0-∘**¥**≭K, CWL <u>\_010</u>\_\_\_ CN5 °,∎‡≮, 10kΩ ₀ ₽¥\$K, Twisted-pair EMGS -10KΩ 10KΩ 10kΩ 10kΩ shield cable ~)-בוב ZSPD 1.5kΩ בובע Use a relay or open-collector transistor to input signal $\downarrow \frown$ $\searrow$ 24V ן≓ע ┼─॒─ Viring of DI signal, for the use of hternal power supply Wiring of DI signal, for the use of external power supply, inductive load ן≒י Caution: Because this notocoupler is a unidirectional oupler, please pay close attention בוב on the current direction of input -Appres 4.7KD pulse command. בוב 1+ (04.7K) ₽\* High-speed pulse input (Line receiver) SON . \$ A phase pulse Servo Drive \$ 3 phase pulse Encoder pulse output (PG Dividing Ratio Output) IGN 2KO \$ ring of DI signal, for the use of Wiring of DI signal, for the use of external power supply Z phase puls rnal power supply Servo Drive Z phase open ILSE 2KG 100Ω 2KΩ Max. outpu current 3A voltage 50\ **4** 至子 4.7K.0 - Acertar Acertar \_≞₽₹ NOTE: Caution: Ensure \*1. 400W and below drives do not provide that the ground terminal of the con and the servo drive should be conr to each other. built-in regenerative resistor. \*2. The coil of brake has no polarity. \*3. Please refer to SINK / SOURCE modes Caution: Do not use dual power supply. Failure to observe this caution may result in damage to the

servo drive and servo motor.

# Speed (S) Control Mode

2201





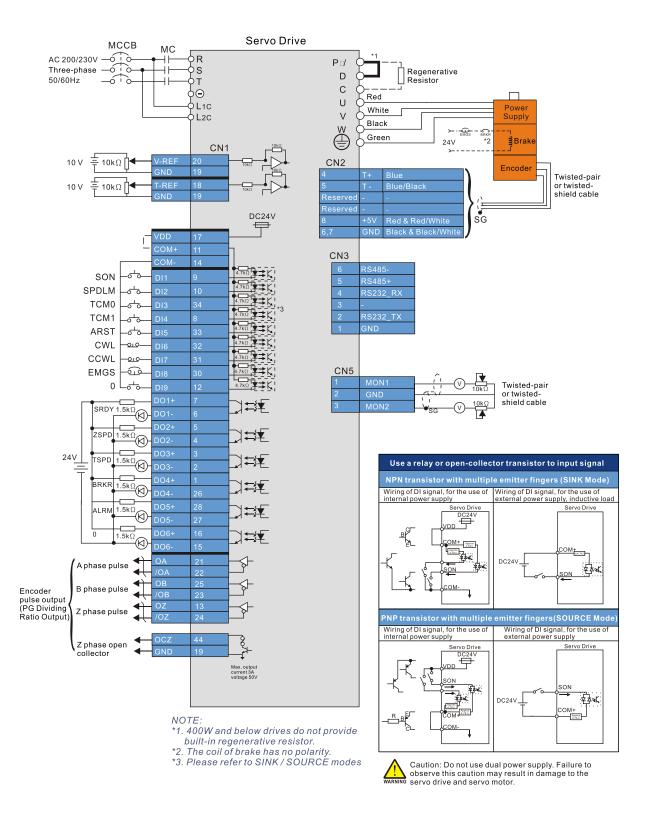
Ning servo drive and servo motor.

observe this caution may result in damage to the

# **Standard Connection Example**

# Torque (T) Control Mode

1otio



# **Regenerative Resistor**

Servo Drive	Recommended S Built-in Regener	Specifications for ative Resistor	Recommended Specifications for	Min. Allowable
(kW)	Resistance (Ohm) (parameter P1-52)	Capacity (Watt) (parameter P1-53)	External Regenerative Resistor	Resistance (Ohm)
0.1			80Ω	60Ω
0.2			80Ω	60Ω
0.4			80Ω	60Ω
0.75	100Ω	60W	80Ω	60Ω
1.0	40Ω	60W	40Ω	30Ω
1.5	40Ω	60W	40Ω	30Ω
2.0	40Ω	60W	30Ω	15Ω
3.0	40Ω	60W	30Ω	15Ω

Note:

220

♦ There is no built-in regenerative resistor for 400W and below ASDA-B2 series servo drive. + When the fault, ALE05 (Regeneration Error) occurs, please increase the regenerative resistor capacity or decrease the regenerative resistor resistance (the regenerative resistor resistance should not be less than the minimum allowable resistance listed in the above table.

• If the situation could not be improved after increasing the regenerative resistor capacity or decreasing the regenerative resistor resistance,

please purchase regenerative resistor module.

When combining multiple small-capacity regenerative resistors in parallel to increase the regenerative resistor capacity, make sure that the total resistance value of the regenerative resistors should not be less than the minimum allowable resistance listed in the above table

# **Safety Information**

Global Standards	ASDA-B2 series is i.e. IEC and EN, etc			
	EN61000-4-6	Level 3		
	EN61000-4-3	Level 3		
EMS standard	EN61000-4-2	Level 2 and		
EMS Standard	EN61000-4-4	Level 3		
	EN61000-4-8	Level 4		
	EN61000-4-5	Level 3		
Conducted & Radiated Emissions	Complies with EN5	50011 Class		
CE Marking	CE recognized. Complies with D EMC Directive 2004/108/EC.			
Drotoction Dograd	IEC/EN50178, IE	C/EN60529		
Protection Degree	IP20			
Vibration	1G less than 20Hz,	0.6G 20 to 50		
Shock	15gn 11ms. Complies with IEC/E			
Pollution Degree	Degree 2. Complies	with IEC/EN		
Ambient Temperature	Operating: 0°C~55° forced o Storage: -20°C~65°	ooling will be		
	ASD-B2-0121-B, ASD-B2-0221 Natural Air Circulation			
Cooling Type	ASD-B2-1021-B, ASD-B2-1521-			
Altitude	Altitude 1000m or lo	ower above s		

IEC: International Electrotechnical Commission EN: Europaischen Normen EMC: Electromagnetic Compatibility IP: Ingress Protection Ratings



fully comply with demanding international standards, ds of industrial automation technology.

13

A Group 1, with external EMC filter

Directive 2006/95/EC of the European Parliament and

50Hz. Complies with IEC/EN50178

/EN600028-2-27

N61800-5-1

ting temperature exceeds the specifications, pe required.)

1-B,ASD-B2-0421-B,ASD-B2-0721-B

1-B,ASD-B2-2023-B, ASD-B2-3023-B Fan Cooling

sea level

Motion ASDA-B2 AC-Servo Motor and Drive

# Specifications

	ASDA-B2 Series		100W	200W	400W	750W	1kW	1.5kW	2kW	3kW		
			01	02	04	07	10	15	20	30		
Supply	Phase /	Voltage		•			50/60Hz 50/60Hz		170~2	-phase 55VAC 0Hz 5%		
Power Supply	Continuous C	Output Current	0.9 Arms	1.55 Arms	2.6 Arms	5.1 Arms	7.3 Arms	8.3 Arms	13.4 Arms	19.4 Arms		
	Cooling S	System	Natural Air Circulation Fan Cooling									
	Encoder Re Feedback F				1	7-bit (160	,000 p/re	v)				
	Control of M	ain Circuit				SVPWM	l Control					
	Tuning N	Nodes				Auto /	Manual					
	Dynamic	Brake		None				Built-in				
	Max. Input Pເ	ulse Frequency	Max. 5					lax. 4Mpp Open colle		ceiver)		
ode	Puls	Pulse Type Pulse + Direction					3 phase ;	CCW puls	se + CW p	ulse		
ol M		nd Source		E	xternal p	ulse train	/ Internal	paramete	ers			
ontr	Smoothir	ng Strategy			Lov	v-pass an	d Moving	filter				
Position Control Mode	Electro	onic Gear		Electronic gear N/M multiple N: 1 ~( 2 <sup>26</sup> -1 ), M: 1 ~( 2 <sup>31</sup> -1 ) (1/50 <n m<25600)<="" td=""></n>								
Pos	Torque Lim	it Operation				Set by pa	arameters	;				
	Feed Forward	Compensation			\$	Speed Co	ntrol Mod	le				
		Voltage Range				0 ~ ±	$10 V_{DC}$					
	Analog Input Command	Input Resistance		10К								
	Command	Time Constant				2.2	2 us					
ode	Speed Co	ontrol Range <sup>*1</sup>				1:5	000					
Control Mode	Comma	and Source		Ext	ernal ana	log signa	l / Interna	al paramet	ters			
ontre	Smoothi	ing Strategy			Low	-pass and	S-curve	filter				
	Torque Lii	mit Operation			Set by pa	rameters	or via An	alog input	:			
Speed		cy Response acteristic				Maximu	m 500Hz					
			0	.01% or le	ess at loa	d fluctuat	ion 0 to 10	00% (at ra	ited spee	d)		
	Speed Fluc	tuation Rate <sup>*2</sup>		0.01% or	less at po	wer fluct	uation ±10	0% (at rat	ed speed	)		
				0.01%			t tempera at rated s	ture flucti peed)	uation			
de		Voltage Range				0 ~ ±	$10 V_{DC}$					
Torque Control Mode	Analog Input Command	Input Resistance				10	Ж					
ntro		Time Constant				2.2	us					
Co	Comma	and Source		Ext	ernal ana	log signa	I / Interna	al parame	ters			
rque	Smoothi	ng Strategy				Low-pa	iss filter					
L0	Speed Lir	ed Limit Operation Parameter Setting or via Analog input										

	ASDA-B2 Series		100W	200W	400W	750W	1kW	1.5kW	2kW	3kW	
	ASDA-I	32 Series	01	02	04	07	10	15	20	30	
	Analog Mo	onitor Output	Mon	itor signa	l can set	by param	eters (Ou	tput volta	ge range:	±8V)	
Di	gital Input/ Output	Input	Servo On, Reset, Gain switching, Pulse clear, Zero speed CLAMP, Speed/Torque limit enabled, Emergency stop, Forward / Reverse inhibit limit, Position / Speed mode switching, Speed / Torque mode switching, Torque / Position mode switching, Feed step selection input, Feed step mode input, Auto run input, Electronic gear ratio (Numerator) selection								
			Encoder signal output (A, B, Z Line Driver / Z Open colle							or)	
Output Output Servo ready, Servo On, At Zero speed, At Speed At Positioning completed, At Torques I Servo alarm (Servo fault) activated, Electromagnet Homing completed, Output overload wa Servo warning activated, Internal position comma								orques lir omagnetio rload wari	nit, c brake co ning	ontrol,	
	Protective	Protective Functions Protective Functions Overcurrent, Overvoltage, Undervoltage, Regeneration error, O Overspeed, Abnormal pulse control command, Excessive dev Watch dog execution time out, Encoder error, Adjustment e Emergency stop activated, Reverse/ Forward limit switch e IGBT temperature error, Memory error, DSP communication Serial communication time out, Command write-in error terminals with short circuit protection (U, V, W, CN1, CN2, CN3)						iation, rror, rror, error,			
	Communica	ation Interface	RS-232 / RS-485 / CANopen / USB								
	Insta	allation Site	Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)						and gas		
	ŀ	Altitude		1	Altitude 1	000m or lo	ower abo	ve sea lev	el		
	Atmospl	heric Pressure				86kPa -	- 106kPa				
	Operatin	ng Temperature		0°C ~ 5		erating te l cooling v		re is abov uired)	e 45°C,		
ţ	Storage	e Temperature				-20℃	~65℃				
nme	Н	lumidity			0 to	90% (non	-condens	ing)			
Environment	V	ibration	20	Hz以下 9	.80665m/	/s²(1G)	<sup>,</sup> 20 ~ 50	Hz 5.88m	/ s² ( 0.60	G)	
En	IF	PRating				IP	20				
	Pow	ver System				TN Sy	stem*3				
	Aj	oprovals	IEC/EN 61800-5-1								

Footnote:

220V

- \*1 Rated rotation speed: When full load, speed ratio is defined as the minimum speed (the motor will not pause).
- \*2 When command is rated rotation speed, the speed fluctuation rate is defined as: (Empty load rotation speed - Full load rotation speed) / Rated rotation speed
- \*3 TN system: A power distribution system having one point directly earthed, the exposed conductive parts of the installation being connected to that points by protective earth conductor.

(13)





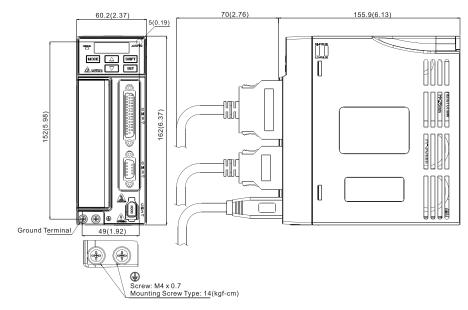




# **Dimensions**

Notio

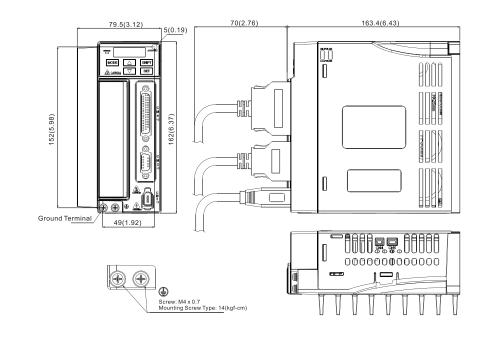
# ● 100W/200W/400W





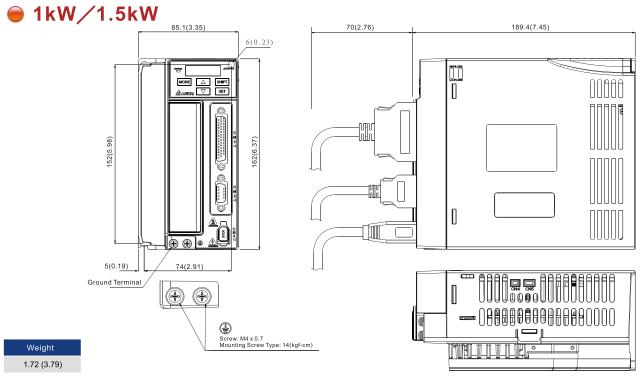
1)Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)). 2)Dimensions and weights of the servo drives may be revised without prior notice.

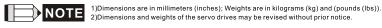
### **750W**



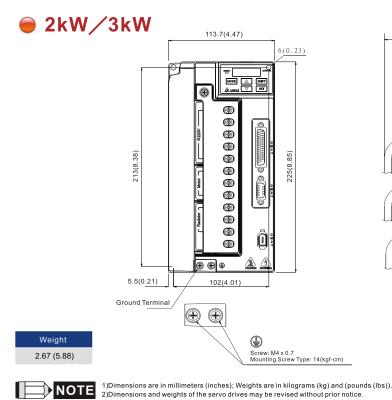


1)Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)). 2)Dimensions and weights of the servo drives may be revised without prior notice.

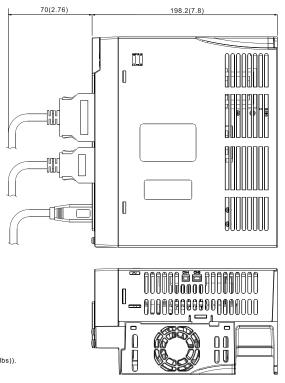




2201







# Notio

(17)

# *АSDA*-В2 AC Servo Motor and Drive

# ECMA Specifications Low Inertia Series

#### C204 C206 Model: ECMA Series 01 04 02

Rated output power (kW)	0.1	0.2	0.4	0.4	0.75	0.75	1.0	1.0	2.0
Rated torque (N-m) <sup>*1</sup>	0.32	0.64	1.27	1.27	2.39	2.39	3.18	3.18	6.37
Maximum torque (N-m)	0.96	1.92	3.82	3.82	7.16	7.14	8.78	9.54	19.1
Rated speed (r/min)			3000			30	00	30	00
Maximum speed (r/min)			5000			30	00	50	00
Rated current (A)	0.90	1.55	2.60	2.60	5.10	3.66	4.25	7.30	12.05
Maximum current (A)	2.70	4.65	7.80	7.24	15.3	11	12.37	21.9	36.15
Power rating (kW/s)	27.7	22.4	57.6	22.1	48.4	29.6	38.6	38.1	90.6
Rotor moment of inertia $(\times 10^{-4} \text{kg.m}^2)$ (Without brake)	0.037	0.177	0.277	0.68	1.13	1.93	2.62	2.65	4.45
Mechanical time constant (ms)	0.75	0.80	0.53	0.73	0.62	1.72	1.20	0.74	0.61
Torque constant-KT (N-m/A)	0.36	0.41	0.49	0.49	0.47	0.65	0.75	0.44	0.53
Voltage constant-KE (mV/(r/min))	13.6	16.0	17.4	18.5	17.2	27.5	24.2	16.8	19.2
Armature resistance (Ohm)	9.30	2.79	1.55	0.93	0.42	1.34	0.897	0.20	0.13
Armature inductance (mH)	24.0	12.07	6.71	7.39	3.53	7.55	5.7	1.81	1.50
Electrical time constant (ms)	2.58	4.30	4.30	7.96	8.36	5.66	6.35	9.30	11.4
Insulation class			C	Class A (I	JL), Clas	s B (CE)			
Insulation resistance	>100MΩ · DC 500V								
Insulation strength	1500V AC, 60 seconds								
Weight (kg) (without brake)	0.5	1.2	1.6	2.1	3.0	2.9	3.8	4.3	6.2
Weight (kg) (with brake)	0.8	1.5	2.0	2.9	3.8	3.69	5.5	4.7	7.2
Max. radial shaft load (N)	78.4	196	196	245	245	245	245	490	490
Max. thrust shaft load (N)	39.2	68	68	98	98	98	98	98	98
Power rating (kW/s) (with brake)	25.6	21.3	53.8	22.1	48.4	29.3	37.9	30.4	82.0
Rotor moment of inertia (× 10⁴kg.m²) (with brake)	0.04	0.19	0.30	0.73	1.18	1.95	2.67	3.33	4.95
Mechanical time constant (ms) (with brake)	0.81	0.85	0.57	0.78	0.65	1.74	1.22	0.93	0.66
Brake holding torque [Nt-m (min)]	0.3	1.3	1.3	2.5	2.5	2.5	2.5	8.0	8.0
Brake power consumption (at 20C) [W]	7.2	6.5	6.5	8.2	8.2	8.2	8.2	18.5	18.5
Brake release time [ms (Max)]	5	10	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	25	70	70	70	70	70	70	70	70
Vibration grade ( $\mu$ m)					15				
Operating temperature (°C)					0~40				
Storage temperature (°C)					-10 ~ 80				
Operating humidity			20	~ 90%R	H (non-c	ondensir	ng)		
Storage humidity			20	~ 90%R	H (non-c	ondensir	וg)		
Vibration capacity					2.5G				
IP Rating	IP65 (v				rs are us shaft (an				ised to
Approvals				CE Mark Safety Approved	c AL	US			
Footnote:*1 Rate torque values are continuous permissible values of the motors with rotary m						ks listed below			

C208

07

04

C209

10

07

# : I rune torque values are continuous permissible values at 0~40°C ambient temperature when attaching with the sizes of 1 \*2 For the specifications of the motors with rotary magnetic encoders, please refer to the corresponding standard models. ECMA-\_\_04 / 06 / 08 : 250mm x 250mm x 6mm ECMA-\_\_13 : 400mm x 400mm x 12mm ECMA-\_\_13 : 400mm x 400mm

## Medium / High Inertia Series

3

220V

0

C210

10

20

		E2			E2	18	F218		G213	
Model: ECMA Series	05	10	15	20	20	30	30	03	06	09
Rated output power (kW)	0.5	1.0	1.5	2.0	2.0	3.0	3.0	0.3	0.6	0.9
Rated torque (N-m) <sup>*1</sup>	2.39	4.77	7.16	9.55	9.55	14.32	19.10	2.86	5.73	8.59
Maximum torque (N-m)	7.16	14.32	21.48	28.65	28.65	42.97	57.29	8.59	17.19	21.48
Rated speed (r/min)				00			1500		1000	
Maximum speed (r/min)			30	00					2000	
Rated current (A)	2.9	5.6	8.3	11.01	11.22	16.1	19.4	2.5	4.8	7.5
Maximum current (A)	8.7	16.8	24.81	33.03	33.66	48.3	58.2	7.44	14.49	22.5
Power rating (kW/s)	7.0	27.1	45.9	62.5	26.3	37.3	66.4	10.0	39.0	66.0
Rotor moment of inertia (× 10 <sup>-₄</sup> kg.m²)(Without brake)	8.17	8.41	11.18	14.59	34.68	54.95	54.95	8.17	8.41	11.18
Mechanical time constant (ms)	1.91	1.51	1.11	0.96	1.62	1.06	1.28	1.84	1.40	1.07
Torque constant-KT (N-m/A)	0.83	0.85	0.87	0.87	0.85	0.89	0.98	1.15	1.19	1.15
Voltage constant-KE (mV/(r/min))	30.9	31.9	31.8	31.8	31.4	32.0	35.0	42.5	43.8	41.6
Armature resistance (Ohm)	0.57	0.47	0.26	0.174	0.119	0.052	0.077	1.06	0.82	0.43
Armature inductance (mH)	7.39	5.99	4.01	2.76	2.84	1.38	1.27	14.29	11.12	6.97
Electrical time constant (ms)	12.96	12.88	15.31	15.86	23.87	26.39	16.51	13.55	13.55	16.06
Insulation class				Class	s A (UL),	Class E	8 (CE)			
Insulation resistance				>	100MΩ	DC 500	V			
Insulation strength	1500V AC, 60 seconds									
Weight (kg) (without brake)	6.8	7.0	7.5	7.8	13.5	18.5	18.5	6.8	7.0	7.5
Weight (kg) (with brake)	8.2	8.4	8.9	9.2	17.5	22.5	22.5	8.2	8.4	8.9
Max. radial shaft load (N)	490	490	490	490	1176	1470	1470	490	490	490
Max. thrust shaft load (N)	98	98	98	98	490	490	490	98	98	98
Power rating (kW/s) (with brake)	6.4	24.9	43.1	59.7	24.1	35.9	63.9	9.2	35.9	62.1
Rotor moment of inertia (× 10 <sup>-₄</sup> kg.m²) (with brake)	8.94	9.14	11.90	15.88	37.86	57.06	57.06	8.94	9.14	11.9
Mechanical time constant (ms) (with brake)	2.07	1.64	1.19	1.05	1.77	1.10	1.33	2.0	1.51	1.13
Brake holding torque [Nt-m (min)]	16.5	16.5	16.5	16.5	25.0	25.0	25.0	10.0	10.0	10.0
Brake power consumption (at 20C) [W]	21.0	21.0	21.0	21.0	20.4	20.4	20.4	19.0	19.0	19.0
Brake release time [ms (Max)]	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0
Brake pull-in time [ms (Max)]	25.0	25.0	25.0	25.0	25.0	25.0	25.0	25.0	25.0	25.0
Vibration grade ( $\mu$ m)					1	5				
Operating temperature (°C)					0 ~	· 40				
Storage temperature (°C)					-10	~ 80				
Operating humidity				20~90	%RH(n	on-cond	ensing)			
Storage humidity				20~90	%RH(n	on-cond	ensing)			
Vibration capacity					2.	5G				
IP Rating	IP65						or wher seal mo		seal is us sed))	ed to
Approvals				(	E		) US			
Footnote:*1 Rate torque values are continuous permissible values are conte						neatsinks liste	a below:			

-2 - or the specifications of the motors with rotary magne ECMA-\_\_04 / 06 / 08 : 250mm x 250mm x 6mm ECMA-\_\_10 : 300mm x 300mm x 12mm ECMA-\_\_13 : 400mm x 400mm x 20mm ers, plea SHIFT

CHARGE 00000 ADM-82

MODE

 $\triangle$ 

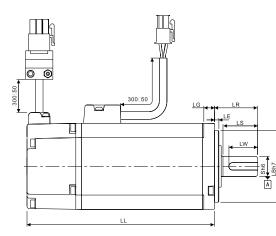


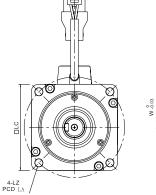


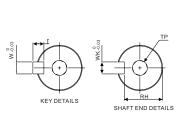
# **Dimensions**

Notio

# Motors - Frame Size 80mm and below (Units: mm)

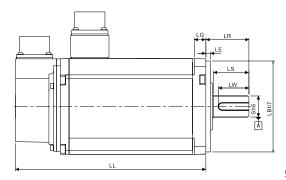






2201

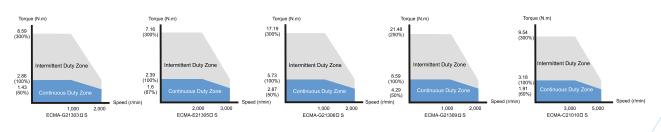
	Motors	- Frame	Size	100mm	~
$\sim$	motor 5	I I UIIIC			



Model	G21303_S	E21305_S
LC	130	130
LZ	9	9
LA	145	145
S	22( <sup>+0</sup> <sub>-0.013</sub> )	22( <sup>+0</sup> <sub>-0.013</sub> )
LB	110( <sup>+0</sup> <sub>-0.035</sub> )	110( <sup>+0</sup> <sub>-0.035</sub> )
LL(Without Brake)	147.5	147.5
LL(With Brake)	183.5	183.5
LS	47	47
LR	55	55
LE	6	6
LG	11.5	11.5
LW	36	36
RH	18	18
WK	8	8
W	8	8
Т	7	7
TP	M6 Depth 20	M6 Depth 20



# Speed-Torque Curves (T-N Curves)



Model	C20401 S	C20602_S	C20604 S	C20804_S	C20807□S	C20907 S	C20910 S
LC	40	60	60	80	80	86	86
LZ	4.5	5.5	5.5	6.6	6.6	6.6	6.6
LA	46	70	70	90	90	100	100
S	8(+0,009)	14( <sup>+0</sup> <sub>-0.011</sub> )	14( <sup>+0</sup> <sub>-0.011</sub> )	14( <sup>+0</sup> <sub>-0.011</sub> )	$19(^{+0}_{-0.013})$	$16(^{+0}_{-0.011})$	16( <sup>+0</sup> <sub>-0.011</sub> )
LB	30( <sup>+0</sup> <sub>-0.021</sub> )	$50(^{+0}_{-0.025})$	$50(^{+0}_{-0.025})$	70(+0 -0.030)	70( <sup>+0</sup> <sub>-0.030</sub> )	80(+0.030)	80(+0 -0.030)
LL(Without Brake)	100.6	105.5	130.7	112.3	138.3	130.2	153.2
LL(With Brake)	136.6	141.6	166.8	152.8	178	161.3	184.3
LS(Without Oil Seal)	20	27	27	27	32	30	30
LS(With Oil Seal)	20	24	24	24.5	29.5	30	30
LR	25	30	30	30	35	35	35
LE	2.5	3	3	3	3	3	3
LG	5	7.5	7.5	8	8	8	8
LW	16	20	20	20	25	20	20
RH	6.2	11	11	11	15.5	13	13
WK	3	5	5	5	6	5	5
W	3	5	5	5	6	5	5
Т	3	5	5	5	6	5	5
TP	M3 Depth 8	M4 Depth 15	M4 Depth 15	M4 Depth 15	M6 Depth 20	M5 Depth 15	M5 Depth 15



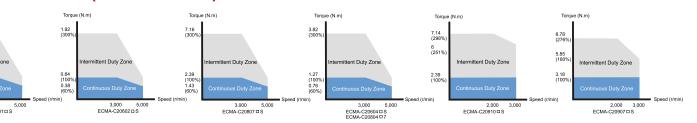


 1. Dimensions are in millimeters. Weights are in kilograms (kg) and (pounds (lbs)).

 2. Dimensions and weights of the servo motor may be revised without prior notice.

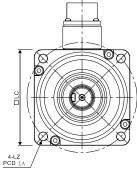
 3. The boxes () in the model names are for optional configurations (keyway, brake and oil seal).

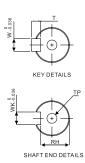
 4. Except ECMA-CM0604PS LL:116,2mm, for the specifications of the motors with rotary magnetic encoders, please refer to the corresponding standard models.





# 130mm (Units: mm)





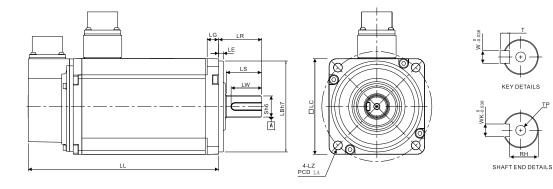
G21309 S G21306 S C21010 S 130 130 100 9 9 9 145 145 115 22(+0 -0.013) 22(+0 -0.013) 22(+0 -0.013)  $110(^{+0}_{-0.035})$  $110(^{+0}_{-0.035})$ 95(<sup>+0</sup><sub>-0.035</sub>) 147.5 163.5 153.3 183.5 198 192.5 47 47 37 55 55 45 6 6 5 11.5 11.5 12 36 36 32 18 18 18 8 8 8 8 8 8 7 7 7 M6 M6 M6 Depth 20 Depth 20 Depth 20

Dimensions are in millimeters. Weights are in kilograms (kg) and (pounds (lbs)).
 Dimensions and weights of the servo motor may be revised without prior notice.
 The boxes (□) in the model names are for optional configurations (keyway, brake and oil seal).
 For the specifications of the motors with rotary magnetic encoders, please refer to the corresponding standard models.

# Dimensions

Notio

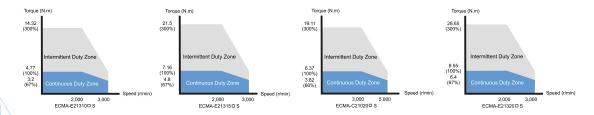
# Motors - Frame Size 100mm ~ 130mm (Units: mm)



Model	E21310 <u></u> S	E21315_S	C21020_S	E21320_S
LC	130	130	100	130
LZ	9	9	9	9
LA	145	145	115	145
S	22( <sup>+0</sup> <sub>-0.013</sub> )	22( <sup>+0</sup> <sub>-0.013</sub> )	22( <sup>+0</sup> <sub>-0.013</sub> )	22( <sup>+0</sup> <sub>-0.013</sub> )
LB	110( <sup>+0</sup> <sub>-0.035</sub> )	110( <sup>+0</sup> <sub>-0.035</sub> )	95( <sup>+0</sup> <sub>-0.035</sub> )	110(+0 -0.035)
LL(Without Brake)	147.5	167.5	199	187.5
LL(With Brake)	183.5	202	226	216
LS	47	47	37	47
LR	55	55	45	55
LE	6	6	5	6
LG	11.5	11.5	12	11.5
LW	36	36	32	36
RH	18	18	18	18
WK	8	8	8	8
W	8	8	8	8
Т	7	7	7	7
TP	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20

#### 1. Dimensions are inmillimeters. Weights are in kilograms (kg) and (pounds(lbs)) 2. Dimensions and weightsof the servo motormay be revised withoutprior notice. 3. The boxes () in the modelnames are for optionalconfigurations (keyway, bra (evway, brakeand oil seal).

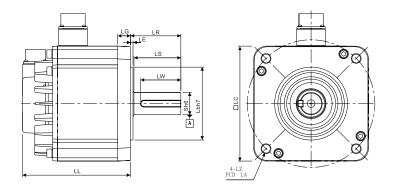
# Speed-Torque Curves (T-N Curves)



# Motors - Frame Size 180mm and above (Units: mm)

220V

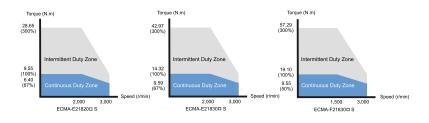
2.



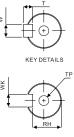
Model	E21820_S	E21830_S	F21830_S
LC	180	180	180
LZ	13.5	13.5	13.5
LA	200	200	200
S	35( <sup>+0</sup> <sub>-0.016</sub> )	35( <sup>+0</sup> <sub>-0.016</sub> )	35( <sup>+0</sup> <sub>-0.016</sub> )
LB	114.3( <sup>+0</sup> <sub>-0.035</sub> )	114.3(+0 .035)	114.3( <sup>+0</sup> <sub>-0.035</sub> )
LL(Without Brake)	169	202.1	202.1
LL(With Brake)	203.1	235.3	235.3
LS	73	73	73
LR	79	79	79
LE	4	4	4
LG	20	20	20
LW	63	63	63
RH	30	30	30
WK	10 <sub>-0.036</sub>	10 <sub>-0.036</sub>	10 <sub>-0.036</sub>
W	10 <sub>-0.036</sub>	10 <sub>-0.036</sub>	10 <sub>-</sub> 0 <sub>.036</sub>
Т	8	8	8
TP	M12 Depth 25	M12 Depth 25	M12 Depth 25
		1. Dimensions are inmillimeters. Weights a	re in kilograms (kg) and (pounds(lbs)).



# Speed-Torque Curves (T-N Curves)







SHAFT END DETAILS

Dimensions are inmillimeters. Weights are in kilograms (kg) and (pounds(lbs)).
 Dimensions and weights of the servo motormay be revised withoutprior notice.
 The boxes (□) in the modelnames are for optional configurations (keyway, brakeand oil seal)



# **ASDA-B2** Optional Accessories

# Optional Units

#### **Power Cable**

without brake.

Aotio

- 3m and 5m standard cables are available.
- Customized service is offering to meet
- the needs of the customers.Two types are selectable: with brake and

#### **CN1 I/O Connector**

■ Used to connect to external (host) controller



#### **Encoder Cable**

- 3m and 5m standard cables are available.
- Customized service is offering to meet the needs of the customers.





2201



#### **Regenerative Resistor**

■ 400W/40Ohm and 1kW/20Ohm two kinds of specifications are available.

4Regarding the selection of regenerative resistor, please refer to the table of regenerative resistor specifications on catalogue page 12.

#### **RS-485 Connector**

Used to connect multiple Delta ASDA series products by RS-485 interface through Modbus serial communication.



#### ASD-Soft Software Communication Cable (for PC)

# **ASDA-B2 Optional Accessories**

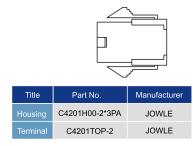
# Power Connector

#### ASDBCAPW0000

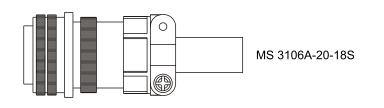
Aotio



#### ASDBCAPW0100

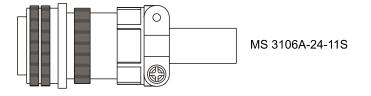


#### ASD-CAPW1000



#### ASD-CAPW2000

KST: SVBL1-3.7

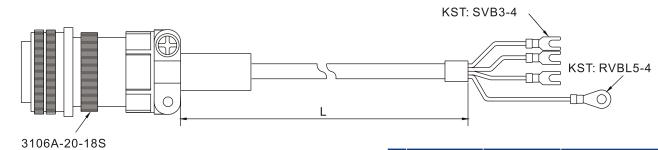


# Power Cable

2

2201

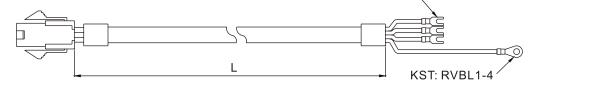
#### ASD-CAPW1203/1205

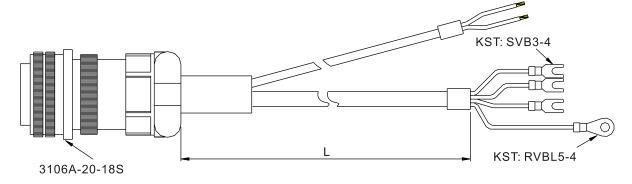


#### ASD-CAPW1303/1305

# Power Cable

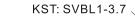
#### ASDBCAPW0203/0205

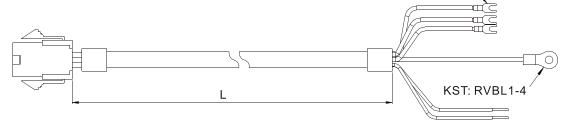




# Title Part No. Manufacturer Title Part No. L Housing C4201H00-2\*2PA JOWLE 1 ASDBCAPW0203 3000 0.50 118 0.2 Terminal C4201TOP-2 JOWLE 2 ASDBCAPW0205 5000 0.50 197 0.2

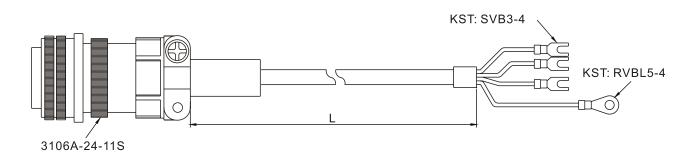
#### ASDBCAPW0303/0305





Title	Part No.	Manufacturer	Title	Part No.	L.	
nue	Fall NO.	Manufacturer	1100		mm	inch
Housing	C4201H00-2*3PA	JOWLE	1	ASDBCAPW0303	3000 □50	118 🛛
Terminal	C4201TOP-2	JOWLE	2	ASDBCAPW0305	5000 □50	197 🗆

#### ASD-CAPW2203/2205





Title	Part No. Straight		L		
nue	Fait NO.	Straight	mm	inch	
1	ASD-CAPW1203	3106A-20-18S	3000 □ 50	118 🗆 2	
2	ASD-CAPW1205	3106A-20-18S	5000 🗆 50	197 🗆 2	

Title	Part No.	Straight	L	_
nue	Fall NO.	Straight	mm	inch
1	ASD-CAPW1303	3106A-20-18S	3000 □ 50	118 🗆 2
2	ASD-CAPW1305	3106A-20-18S	5000 🗆 50	197 🗆 2

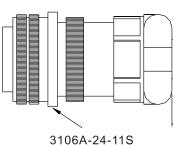
Title	Part No.	Straight		
Title	Fait NO.	Straight	mm         inch           3000         50         118         2	inch
1	ASD-CAPW2203	3106A-24-11S	3000 🗆 50	118 🗆 2
2	ASD-CAPW2205	3106A-24-11S	5000 🗆 50	197 🗆 2

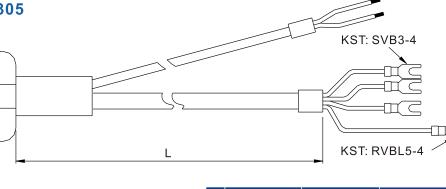
# **ASDA-B2** Optional Accessories

# Power Cable

Aotio

#### ASD-CAPW2303/2305





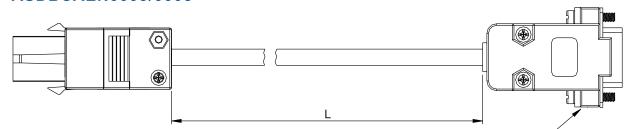
Title	Part No.	Straight	L		
nue	T art NO.	Otraight	mm	inch	
1	ASD-CAPW2303	3106A-24-11S	3000 🗆 50	118 🗆 2	
2	ASD-CAPW2305	3106A-24-11S	5000 □50	197 🗆 2	

# Encoder Cable

2201

O

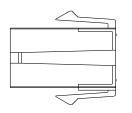
ASDBCAEN0003/0005

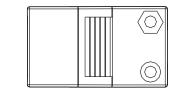


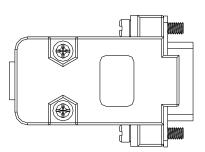
			Title	Part No.	Manufacturer	
Title	Part No.	mm	- inch	Housing	AMP(1-172161-9)	AMP
1	ASDBCAEN0003	3000 🗆 50	118 🗆 2	Terminal	AMP(170359-3)	AMP
2	ASDBCAEN0005	5000 🗆 50	197 🗆 2	CLAMP	DELTA(34703237XX)	DELTA

# Encoder Connector

#### ASDBCAEN0000



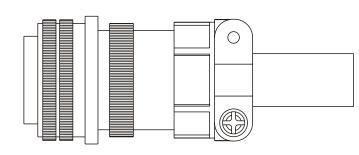




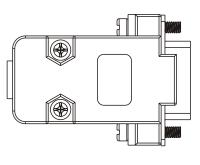
D-SUB Connector 9P

Title	Part No.	Manufacturer
Housing	AMP(1-172161-9)	AMP
Terminal	AMP(170359-3)	AMP
CLAMP	DELTA(34703237XX)	DELTA

#### ASDBCAEN1000



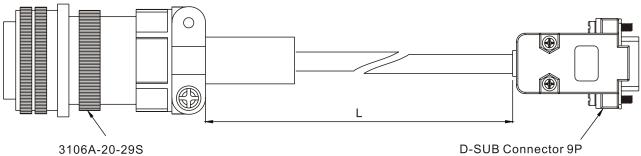
3106A-20-29S



D-SUB Connector 9P

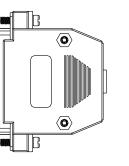
# Encoder Cable

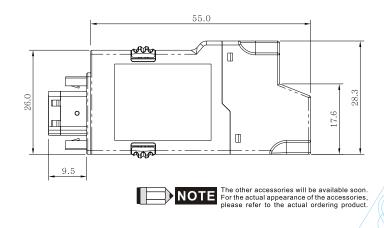
#### **ASDBCAEN1003/1005**





ASDBCNDS0044





D-SUB 44 PIN PLUG





#### **D-SUB** Connector 9P

# RS-485 Connector

#### **ASD-CNIEOB06**

# **Accessories Combinations**

1otio

# Servo Drive, Servo Motor and Accessories Combinations

#### 100 W Servo Drive and 100W Low Inertia Servo Motor (ECMA Series)

Servo Drive	ASD-B2-0121-B						
Low Inertia Servo Motor	ECMA-C20401 S						
	Withou	t Brake	With	Brake			
	3M	5M	3M	5M			
Cable	Motor Power Cable ASDBCAPW0203	Motor Power Cable ASDBCAPW0205	Motor Power Cable ASDBCAPW0303	Motor Power Cable ASDBCAPW0305			
	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005			
Connector		Power Connector	ASDBCAPW0000				
Connector		Encoder Connecto	or ASDBCAEN0000				

#### 200W Servo Drive and 200W Low Inertia Servo Motor

Servo Drive	ASD-B2-0221-B					
Low Inertia Servo Motor	ECMA-C20602 <b>D</b> S					
	Withou	ut Brake	With	Brake		
	3M	5M	3M	5M		
Cable	Motor Power Cable ASDBCAPW0203	Motor Power Cable ASDBCAPW0205	Motor Power Cable ASDBCAPW0303	Motor Power Cable ASDBCAPW0305		
	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005		
Connector	Power Connector	ASDBCAPW0000	Power Connector ASDBCAPW0100			
Connector		Encoder Connecto	or ASDBCAEN0000			

#### 400W Servo Drive and 400W Low Inertia Servo Motor

Servo Drive	ASD-B2-0421-B					
Low Inertia Servo Motor	ECMA-C20604 <b>□</b> S ECMA-C20804 <b>□</b> 7 ECMA-CM0604PS					
	Without Brake		With Brake			
	3M	5M	3M	5M		
Cable	Motor Power Cable ASDBCAPW0203	Motor Power Cable ASDBCAPW0205	Motor Power Cable ASDBCAPW0303	Motor Power Cable ASDBCAPW0305		
	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005		
<b>2</b>	Power Connector	ASDBCAPW0000	Power Connector ASDBCAPW0100			
Connector		Encoder Connecto	r ASDBCAEN0000			

#### 400W Servo Drive and 500W Medium Inertia Servo Motor

2201

Servo Drive	ASD-B2-0421-B					
Medium Inertia Servo Motor	ECMA-E21305 <b>S</b>					
Cable	Withou	ut Brake	With I	Brake		
	3M	5M	3M	5M		
	Motor Power Cable ASDBCAPW1203	Motor Power Cable ASDBCAPW1205	Motor Power Cable ASDBCAPW1303	Motor Power Cable ASDBCAPW1305		
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005		
O a resta e ta r	Power Connector ASDBCAPW1000					
Connector		Encoder Connector ASDBCAEN1000				

#### 400W Servo Drive and 300W High Inertia Servo Motor

Servo Drive	ASD-B2-0421-B					
High Inertia Servo Motor	ECMA-G21303 <b></b> S					
	Withou	ut Brake	Wit	h Brake		
	3M	5M	3M	5M		
Cable	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305		
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005		
Connector	Power Connector ASD-CAPW1000					
Connector		Encoder Connector ASDBCAEN1000				

#### 750W Servo Drive and 750W Low Inertia Servo Motor

Servo Drive	ASD-B2-0721-B				
Low Inertia Servo Motor	ECMA-C20807 <b>□</b> S ECMA-C20907 <b>□</b> S				
	Without Brake		With Brake		
	3M	5M	3M	5M	
Cable	Motor Power Cable ASDBCAPW0203	Motor Power Cable ASDBCAPW0205	Motor Power Cable ASDBCAPW0303	Motor Power Cable ASDBCAPW0305	
	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005	Encoder Cable ASDBCAEN0003	Encoder Cable ASDBCAEN0005	
<b>a</b> i	Power Connector ASDBCAPW0000 Power Connector ASDBCAPW0100			ASDBCAPW0100	
Connector	Encoder Connector ASDBCAEN0000				



# **Accessories Combinations**

1otio

# Servo Drive, Servo Motor and Accessories Combinations

#### 7750W Servo Drive and 600W High Inertia Servo Motor

Servo Drive	ASD-B2-0721-B			
High Inertia Servo Motor	ECMA-G21306 <b>□</b> S ECMA-GM1306PS			
	Withou	ut Brake	With Brake	
	3M	5M	3M	5M
Cable	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005
Connector	Power Connector ASD-CAPW1000			
		Encoder Connecto	rASDBCAEN1000	

#### 1kW Servo Drive and 1kW Low Inertia Servo Motor

Servo Drive	ASD-B2-1021-B			
Low Inertia Servo Motor	ECMA-C21010□S ECMA-C20910□S			
	Without Brake		With Brake	
	3M	5M	3M	5M
Cable	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005
Connector	Power Connector ASDBCAPW1000			
Connector		Encoder Connecto	rASDBCAEN1000	

#### 1kW Servo Drive and 1kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-1021-B			
Medium Inertia Servo Motor	ECMA-E21310 S			
	With	out Brake	Witl	h Brake
	3M	5M	3M	5M
Cable	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005
Connector	Power Connector ASD-CAPW1000			
		Encoder Connecto	rASDBCAEN1000	

#### 1kW Servo Drive and 900W High Inertia Servo Motor

220V

Servo Drive	ASD-B2-1021-B				
High Inertia Servo Motor	ECMA-G21309 <b>□</b> S ECMA-GM1309PS				
	Without Brake		With	With Brake	
Cable	3M	5M	3M	5M	
	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305	
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	
O a restant	Power Connector ASD-CAPW1000				
Connector	Encoder Connector ASDBCAEN1000				

#### 1.5kW Servo Drive and 1.5kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-1521-B				
Medium Inertia Servo Motor	ECMA-E21315 <b></b> S				
	With	out Brake	Wit	h Brake	
	3M	5M	3M	5M	
Cable	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305	
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	
Connector	Power Connector ASD-CAPW1000				
		Encoder Connecto	or ASDBCAEN1000		

#### 2kW Servo Drive and 2kW Low Inertia Servo Motor

Servo Drive		ASD-B2-2023-B			
Low Inertia Servo Motor	ECMA-C21020 <b></b> S				
	With	out Brake	Witl	h Brake	
	3M	5M	3M	5M	
Cable	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305	
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	
	Power Connector ASD-CAPW1000				
Connector	Encoder Connector ASDBCAEN1000				





# **Accessories Combinations**

Notio

# Servo Drive, Servo Motor and Accessories Combinations

#### 2kW Servo Drive and 2kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-2023-B			
Medium Inertia Servo Motor	ECMA-E21320 <b></b> S			
	Withou	ut Brake	With	Brake
	3M	5M	3M	5M
Cable	Motor Power Cable ASD-CAPW1203	Motor Power Cable ASD-CAPW1205	Motor Power Cable ASD-CAPW1303	Motor Power Cable ASD-CAPW1305
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005
Connector		Power Connector	ASD-CAPW1000	
		Encoder Connecto	rASDBCAEN1000	

Servo Drive	ASD-B2-2023-B			
Medium Inertia Servo Motor	ECMA-E21820 <b></b> S			
	Withou	ut Brake	With Brake	
	3M	5M	3M	5M
Cable	Motor Power Cable ASD-CAPW2203	Motor Power Cable ASD-CAPW2205	Motor Power Cable ASD-CAPW2303	Motor Power Cable ASD-CAPW2305
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005
Connector	Power Connector ASDBCAPW2000			
		Encoder Connecto	rASDBCAEN1000	



#### 3kW Servo Drive and 3kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-3023-B				
Vedium Inertia Servo Motor	ECMA-E21830 <b>D</b> S				
	Withou	With	Brake		
	3M	5M	3M	5M	
Cable	Motor Power Cable ASD-CAPW2203	Motor Power Cable ASD-CAPW2205	Motor Power Cable ASD-CAPW2303	Motor Power Cable ASD-CAPW2305	
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	
O a mana a ta m	Power Connector ASD-CAPW2000				
Connector	Encoder Connector ASDBCAEN1000				
Servo Drive		ASD-B2	-3023-B		

Servo Drive	ASD-B2-3023-B				
Medium Inertia Servo Motor	ECMA-F21830 <b>S</b>				
	Without Brake With Brake				
	3M	5M	3M	5M	
Cable	Motor Power Cable ASD-CAPW2203	Motor Power Cable ASD-CAPW2205	Motor Power Cable ASD-CAPW2303	Motor Power Cable ASD-CAPW2305	
	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	Encoder Cable ASDBCAEN1003	Encoder Cable ASDBCAEN1005	
	Power Connector ASDBCAPW2000				
Connector	Encoder Connector ASDBCAEN1000				

